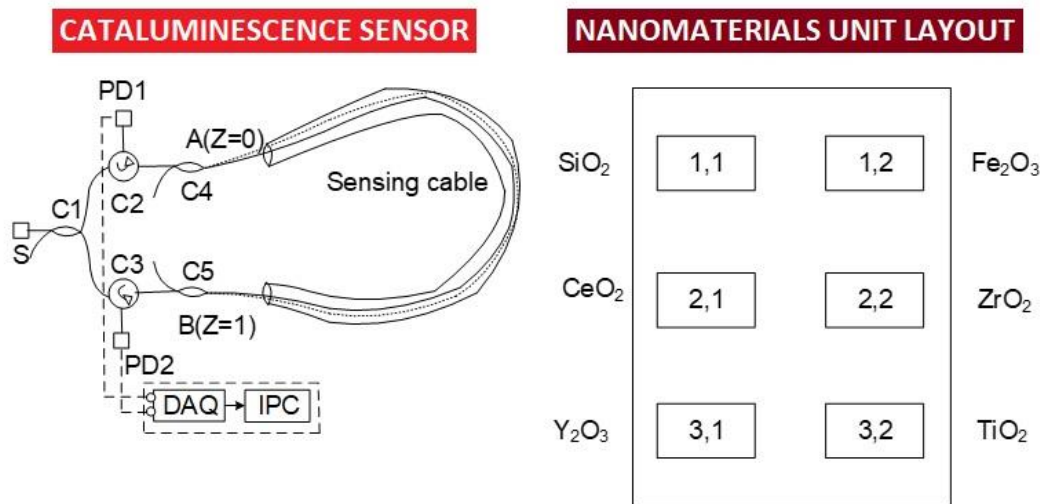


# Nano Sensor for Near Zero Emission Monitoring of Sulfur Hexafluoride

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## Graphical Abstract

### Abstract

Aiming at the problems of long monitoring time, low sensitivity and low precision of traditional methods, a nano sensor for near zero emission monitoring of sulfur hexafluoride (SF<sub>6</sub>) was proposed. The characteristics of SF<sub>6</sub> gas were analyzed. The infrared spectrum of SF<sub>6</sub> gas was obtained by spectral absorption method. The laser of Laixi series is used as the hardware of SF<sub>6</sub> gas monitoring. The nano sensor array is designed, and the near zero emission state of SF<sub>6</sub> is monitored by using the nano sensor node optimization method. The experimental results show that compared with the traditional method, the nano sensor method can shorten the monitoring time (less than 3.0 seconds), improve the monitoring sensitivity and accuracy. The results show that the method can monitor the air emission and environmental pollution accurately and timely.

**Keywords:** Nanosensor, Sulfur Hexafluoride, Near Zero Emission, Sensor Array, Node Optimization.

### 1. Introduction

With the rapid development of social economy, urban substation building area is becoming smaller and smaller, which requires that the floor area of distribution equipment needs to be further reduced. In order to ensure the insulation and arc extinguishing performance in a limited space, the use of SF<sub>6</sub> equipment will be further promoted (Sekhar et al., 2020; Yamamura et al., 2019). The extensive use of SF<sub>6</sub> equipment, on the one hand, makes power production more safe and reliable; on the other hand, SF<sub>6</sub> gas is more and more likely to cause harm to the environment, equipment, especially the personal health and safety of on-site workers (Morscher and Maxwell, 2019). To ensure the normal operation of the equipment and protect the health and safety of on-site workers, effective means must be taken to monitor the SF<sub>6</sub> gas in the equipment area (Mishra et al., 2019).

The research on the monitoring technology of SF<sub>6</sub> in foreign countries starts earlier, and the development of monitoring construction is much more advanced than that in China. With the in-depth development of the

research, the monitoring of SF<sub>6</sub> zero emission has become a research hotspot in recent years (Blanco-Rayon et al., 2019). For many years, many researches have been carried out on the monitoring of SF<sub>6</sub> leakage at home and abroad. The current SF<sub>6</sub> leakage monitoring technologies at home and abroad are mainly classified into the following categories: ultraviolet imaging remote sensing monitoring, acoustic method, high insulation method, etc. Ultraviolet imaging remote sensing monitoring method has advantages of high detection accuracy, high practicability, high temporal resolution and spatial resolution of ultraviolet imaging. It can intuitively obtain the two-dimensional distribution of pollutant gas concentration and the emission rate, so it plays an important role in monitoring environmental pollution (Zhang et al., 2020). Based on the ultraviolet imaging detection technology, the gas concentration information is obtained, which verifies the great application prospect of this method in remote sensing monitoring of factory chimney and ship exhaust pollution emission. However, the monitoring time of this method is too long, which cannot meet the needs of real-time monitoring (Zuo et al., 2020). The principle of acoustic method is to monitor the sound by using the principle that the speed of sound propagation in SF<sub>6</sub> gas is slower than that in the atmosphere. The 3-026-R002 SF<sub>6</sub> gas alarm of DILO company in Germany can monitor the leakage of SF<sub>6</sub> gas when the content of SF<sub>6</sub> gas in the environment exceeds 2%. The system can connect up to 6 monitoring points. The system is limited due to following main disadvantages, including low monitoring sensitivity, the exceeding the theoretical safety upper limit of 1000 ppm (cm<sup>3</sup>/m<sup>3</sup>), and unsatisfactory monitoring accuracy. The high insulation method is a gas leak detector that uses the high insulation characteristics of SF<sub>6</sub> gas and uses high-voltage corona discharge technology. The 3-033-R00 sulphur hexafluoride gas alarm from DILO in Germany and the TIF5650A/TIF5750A qualitative SF<sub>6</sub> gas leak detector from TIF in the United States can qualitatively monitor the leakage of SF<sub>6</sub> in the environment. This type of instrument needs to be calibrated before use, but is not suitable for long-term real-time monitoring (Garmendia et al., 2019; Toma et al., 2019; Wilde, 2019).

Aiming at the problems of traditional monitoring methods, a nano sensor for near zero emission monitoring of sulfur hexafluoride was proposed (He et al., 2018a). The method of monitoring SF<sub>6</sub> gas leakage with nano sensor designed in this paper has the advantages of low cost and strong practicability. It can quickly and effectively monitor SF<sub>6</sub> gas leakage and the location of leakage point.

## 2. EXPERIMENT

### 2.1. Characteristics of SF<sub>6</sub> Gas

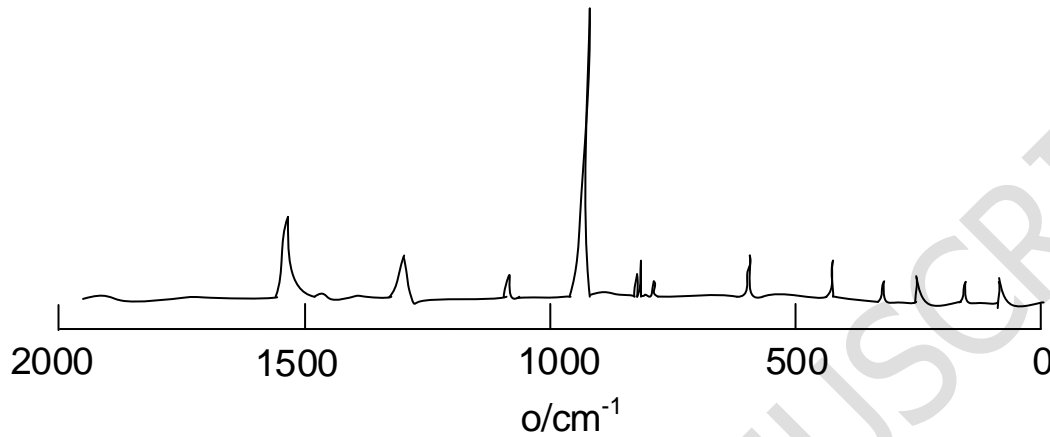
SF<sub>6</sub> has good electrical insulation performance and excellent arc extinguishing performance. It is a new generation of ultra-high voltage dielectric material superior to air and oil. Therefore, SF<sub>6</sub> has been widely used in related equipment of power system (Marchant et al., 2019). SF<sub>6</sub> gas leakage is not easy to be detected, and will seriously reduce the ability of gas insulation and arc extinguishing, bringing security risks to the operation of power equipment. The leakage of toxic decomposition products produced by SF<sub>6</sub> during high voltage arc extinguishing will cause harm to personal safety (Grace and Manju, 2019). Soapy water or hand-held leak detector are normally adopted in early monitoring methods of SF<sub>6</sub> gas leakage, which has low monitoring efficiency and may bring potential danger to the monitoring personnel (Yang et al., 2020). Therefore, it is necessary to fully consider the characteristics of SF<sub>6</sub> gas and design a more effective monitoring method (Ding et al., 2020; Polyanin, 2020; Sun et al., 2019; Wang et al., 2019). The characteristics of SF<sub>6</sub> are described in Table 1.

**Table 1.** Gas characteristics of SF<sub>6</sub>

Nature	Description
Density	The density of SF <sub>6</sub> is about five times that of air;
Appearance and traits	SF <sub>6</sub> is a colorless, odorless, odorless and non-toxic non-combustion gas under normal conditions;
Melting point	Minus 62 degrees Celsius
Boiling point	Minus 51 degrees Celsius
Relative density	1.67
Relative vapor density	5.11
Electrical insulation	Under normal pressure, its insulation capacity is more than 2.5 times that of air
Arc extinguishing characteristics	The arc extinguishing capacity is equivalent to 100 times that of air under the same conditions

Molecular formula	SF <sub>6</sub>
Molecular weight	146.05
Solubility	Slightly soluble in water, ethanol and ether, soluble in potassium hydroxide

According to the characteristics of SF<sub>6</sub> gas described in Table 1, the SF<sub>6</sub> gas adopted in this paper is monitored by spectral absorption method (He et al., 2018b). Based on the strong absorption of SF<sub>6</sub> gas to 10.6  $\mu$ m band light, the adopted method is a more advanced SF<sub>6</sub> monitoring technology in the world (Gosset et al., 2019). The infrared spectrum of SF<sub>6</sub> is shown in Figure 1.



**Figure 1.** Infrared spectrum of SF<sub>6</sub>.

SF<sub>6</sub> gas has a strong absorption effect on the light of a certain wave band. It can be seen from Figure 1 that the light at the frequency of 950 cm<sup>-1</sup> is obviously weakened, and an obvious absorption band of SF<sub>6</sub> gas can be seen in this region. According to the relationship between wavelength and frequency, the absorption band of SF<sub>6</sub> is about 10.6  $\mu$ m.

## 2.2. Hardware design of nano sensor system

According to the characteristics of SF<sub>6</sub> gas, the laser is used as the monitoring hardware to monitor the near zero emission state of SF<sub>6</sub> gas. The laser used in this paper is the lasy series Lasy-5 laser produced by Datong laser (Mihaita et al., 2019), which has the following characteristics as shown in Table 2.

**Table 2.** Laser parameters

Parameter	Numerical value
Average power	5 watts
Average power of pulse	5 watts
Bare waist diameter	2.4 mm
Full angle divergence (milliradians)	Five point five
Wavelength (micron)	Ten point six
Voltage (V)	DC 28
Working temperature	Less than 90%, non condensing
Working pressure	0.7~1.3 Standard atmospheres

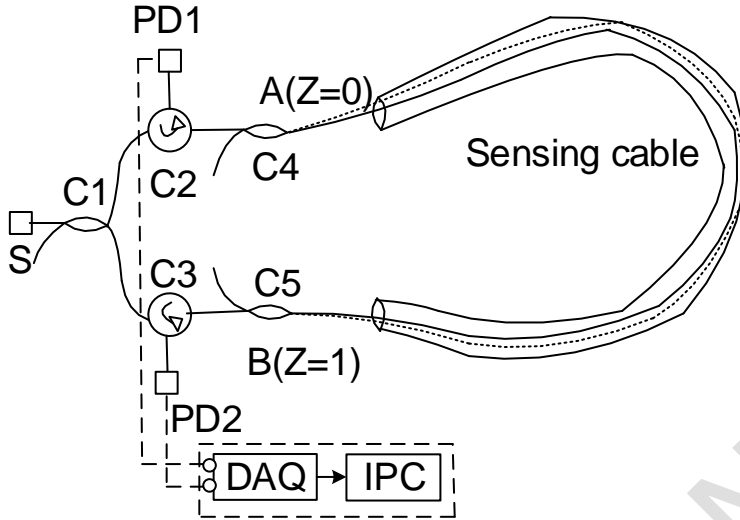
The laser wavelength generated by Lasy-5 laser is 10.6  $\mu$ m, which is just within the strongest absorption band of SF<sub>6</sub> gas (Daniell et al., 2019; Hu et al., 2020; Li et al., 2018; Zhang et al, 2020). Therefore, Lasy-5 laser can meet the requirements of this monitoring design.

## 2.3. Realization of nano sensor for near zero emission monitoring of SF<sub>6</sub>

### 2.3.1. Working Principle of Nanosensor

Nanosensors have been widely used in the fields of biology, chemistry, machinery, aviation, military and so on. Compared with traditional sensors, they have smaller size and improved accuracy. Monitoring gases by

using nanomaterial catalytic luminescence sensors is a typical example of the application of nanomaterials (Tamersit, 2019). In the process of luminescence, the nanomaterial catalytic luminescence sensor mainly consumes oxygen in the air and the monitored gas molecules, and the consumption of solid catalyst is very small. Therefore, as an organic gas sensor, the nanosensor is expected to become a new type of chemiluminescence gas sensor with practical value, which overcomes the shortcomings of traditional chemiluminescence sensor (Pour et al., 2019). Catalytic luminescence signal monitoring can provide rich identification information on the intensity, wavelength and other aspects of monitored objects, and can realize real-time monitoring of the substances with low luminous intensity. The principle of the sensor is shown in Figure 2.



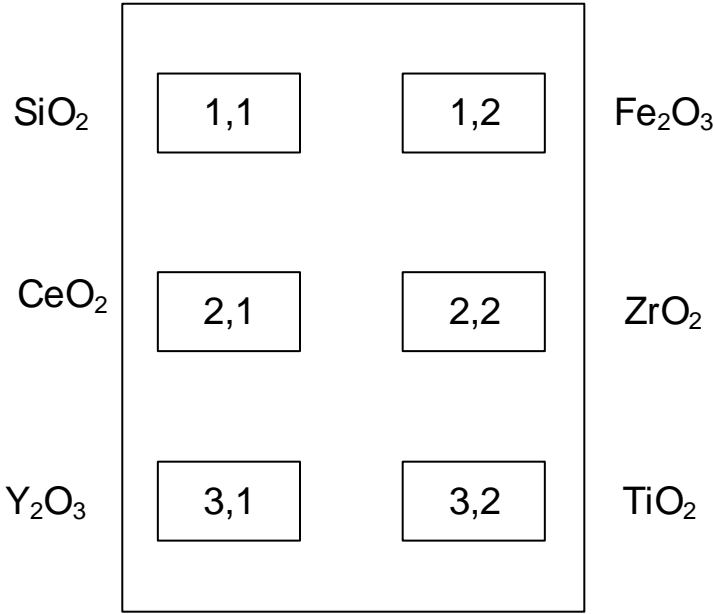
**Figure 2.** Working principle diagram of cataluminescence sensor.

According to Figure 2, when the monitored gas is introduced to the surface of nanomaterials, the catalytic luminescence reaction will occur on the surface of each sensor unit, and the sensor array will record the luminous intensity of each unit.

### 2.3.2. Design of nano sensor array

According to the working principle of the nano sensor, when the organic gas contacts the surface of nanomaterials, chemiluminescence will occur, and its signal will produce different properties of the monitored organic gas and nanomaterials. However, the sensor made of a single nanomaterial can only monitor a certain organic gas, if a variety of different nanomaterials are as sensing units to make sensor arrays, different organic gases can be monitored (El Khalidi et al., 2019; Lv and Kumar, 2020; Song et al., 2020; Yan et al., 2019). Therefore, before monitoring the near zero emission of  $\text{SF}_6$ , the sensor array should be designed based on the catalytic luminescence of nanomaterials. Figure 3 shows the layout of nanomaterials in the nano sensor array (Cordao Neto et al., 2018).

It can be seen from Figure 3 that a  $3 \times 2$  nano sensor array is composed of nanomaterials ( $\text{SiO}_2/\text{Fe}_2\text{O}_3$ ,  $\text{Fe}_2\text{O}_3$ ,  $\text{ZrO}_2$ ,  $\text{CeO}_2$ ,  $\text{Y}_2\text{O}_3$ ,  $\text{TiO}_2$ ) in the designed order, and the area of each unit is about  $8 \times 12 \text{ mm}^2$ .



**Figure 3.** Unit layout of nanomaterials

Considering that the luminous intensity of SF<sub>6</sub> on different nano materials is different, it is necessary to set the luminous intensity threshold of each unit separately, and the error of the data measured by the instrument should be considered. Through studying the luminous intensity of gas on six kinds of materials, the threshold of each unit is set, as shown in Figure 4.

500	0
0	2500
0	0

**Figure 4.** Threshold setting of sensor unit.

### 2.3.3. Nanosensor for near zero emission monitoring of SF<sub>6</sub>

According to the working principle of the nanosensor and the design results of the sensor array,  $F_1 \sim F_6$  is set as the anchor node, which is close to the unknown sensor node. The unknown sensor node is set as  $K_i$ . According to the maximum likelihood estimation principle, at least three anchor nodes are selected for  $K_i$  to estimate its location information.

Taking anchor nodes  $F_1$ ,  $F_2$ , and  $F_3$  as an example, an inner angle  $\beta$  in the array structure needs to meet the following conditions:

$$\cos \beta = \left[ \frac{(F_1 F_2)^2 + (F_1 F_3)^2 - (F_2 F_3)^2}{2(F_1 F_2) \cdot (F_2 F_3)} \right] \quad (1)$$

Where  $F_1 F_2$ ,  $(F_2 F_3)$ ,  $(F_1 F_3)$  are the distances between anchor nodes, respectively.

The collinearity of the anchor node in the near-zero emission state monitoring nano sensor of SF<sub>6</sub> gas can be defined as:

$$\zeta = \max_i \chi_i \quad i = 1, 2, 3, 4, 5, 6 \quad (2)$$

Where  $\chi_i$  represents the inner corner of a triangle formed by using 6 anchor nodes in the monitoring sensor for near-zero emission of SF<sub>6</sub> gas. When formula (2) satisfies the following conditions, it indicates that the sensor nodes are fully collinear.

$$\pi / 6 \leq \zeta \leq \pi \quad (3)$$

According to formula (3), when the collinearity of the anchor node is  $\zeta = \pi / 6$ , the monitoring error of the gas near zero emission state of SF<sub>6</sub> is the smallest. Set the sensor node distance to  $d$  ( $0 < d < 0.6$ ). After the anchor node information is received, we calculate the collinearity of multiple anchor nodes that are closer to the unknown sensor node according to formula (2). When formula (4) is met, the trilateration method is adopted to solve the position information of unknown sensor nodes. Or, an anchor node closer to the unknown sensor node  $K_i$  is selected to replace the candidate anchor node until the following formula (4) is met:

$$0 \leq |\cos \zeta| \leq d \quad (4)$$

It is assumed that the sensor node for near zero emission state monitoring of SF<sub>6</sub> gas is constructed by the node with unknown position (i.e. the unknown node for near zero emission state monitoring of SF<sub>6</sub> gas) and the sensor layer node with known position (i.e. the sensor anchor node for near zero emission state monitoring of SF<sub>6</sub> gas) (Mansouri et al., 2019; Subramanian et al., 2019). Let  $p$  represent the number of monitoring nodes and  $q$  represent the number of anchor nodes, the parameters of the monitoring nodes in the two-dimensional plane are:

$$I = \left| \sum_{p=1}^q X^0(p+1) - X^0(0+1) + 0.5[X^0(q+1) - X^0(0+1)] \right| \quad (5)$$

The position parameter of the nano sensor node for near-zero emission monitoring of SF<sub>6</sub> gas is  $D_{(p,q)}$ , which can be expressed as follows:

$$D_{(p,q)} = [\varpi_N, \varpi_M]^G \quad (6)$$

Where  $\varpi_N$  and  $\varpi_M$  respectively represent the position parameters of the sensor node and the error anchor node of the near-zero emission state of SF<sub>6</sub> gas;  $T$  represents the limiting threshold.

Set  $X(n)$  as the neighbor node of node  $x$ , and  $Y(n)$  as the set of neighbor nodes. The calculation expression is:

$$Y(n) = \sum_{x=1}^q x(i, j) \quad k = 1, 2, \dots, n \quad (7)$$

Where  $(i, j)$  represents a pair of adjacent nodes.

Assuming that the adjacent nano sensor nodes for the near-zero emission monitoring of SF<sub>6</sub> gas are consistent (Magne et al., 2020; Sun et al., 2020), there is a relative measurement relationship between node  $i$  and node  $j$  in the nano sensor for the near-zero emission state monitoring of SF<sub>6</sub> gas, namely:

$$x(i, j) = 1 \quad (8)$$

If there is no relative measurement relationship between node  $i$  and node  $j$  in the nano sensor for near-zero emission monitoring of SF<sub>6</sub> gas, then:

$$x(i, j) = 0 \quad (9)$$

The relative observation information in the nano sensor node of the near-zero emission state monitoring of SF<sub>6</sub> gas includes distance, angle, range, etc. Among them, the distance information is the most accurate, so the relative observation between nodes is selected as the distance observation  $D_{i,j}$ , which can be expressed as follows:

$$D_{i,j} = h_{i,j} + l_{i,j} \quad (10)$$

Where  $h_{i,j}$  represents the measurement error of the true distance between the nano sensor node  $i$  and the node  $j$ ;  $l_{i,j}$  represents the true distance between the nano sensor node  $i$  and the node  $j$ , and the calculation expression is as follows:

$$l_{i,j} = \sqrt{[(o_i - o_j)^2 + (c_i - c_j)^2] \times (o_i c_i + o_j c_j)} \quad (11)$$

Where  $(o_i, o_j)$  and  $(c_i, c_j)$  represent the coordinates in the nano sensor array of nano sensor node  $i$  and node  $j$ , respectively.

Assuming that the set of distance observations obtained by the nano sensor for the near-zero emission monitoring of SF<sub>6</sub> gas is  $D_{ij} = \{d_1, d_2, \dots, d_n\}$ , the specific expression is as follows:

$$D_{ij} = \left( \frac{\|i, j\|^2}{d^2} \right) \times v^k \quad (12)$$

Where  $v^k$  represents the node series observation value.

Then the monitoring joint probability of the nano sensor for the near-zero emission monitoring of SF<sub>6</sub> gas is:

$$E = \sum_{i=1, j=1}^n \frac{\tau_{i,j} \cdot C(i, j)}{\tau_{i,j} \cdot D_{ij}} \quad (13)$$

Where  $\tau_{i,j}$  represents the location parameters of nano sensor node  $i$  and node  $j$ ;  $C(i, j)$  represents the relative observation prior probability between nodes in the nano sensor.

Assuming that the nano sensor anchor node for monitoring near-zero emission state of SF<sub>6</sub> gas has certain online monitoring prior information at the initial moment:

$$\psi_i = \{[w\varphi(x_i) - b]\} \times \varepsilon + \xi_i \quad (14)$$

Where  $\psi_i$  represents the prior probability of the nano sensor node  $i$ ;  $\varphi$  represents the variation coefficient of the reliability coverage of the nano sensor network monitoring area;  $b$  represents the position error parameter of the nano sensor anchor node.

In the traditional method of using sensor nodes to monitor the near zero emission state of SF<sub>6</sub> gas, the location parameters of anchor nodes are not accurate enough, so it is necessary to apply nano sensors in the near zero emission state monitoring of SF<sub>6</sub> gas. The stability of nano sensor is considered in the design of emission condition monitoring, so the design of nano sensor for near zero emission condition monitoring of sulfur hexafluoride is completed.

### 3. Results and Discussion

In order to verify the applicability and effectiveness of the proposed nano sensor for near zero emission monitoring of SF<sub>6</sub>, relevant experimental tests were designed. In the experiment, in order to highlight the advantages of the proposed method, the ultraviolet imaging remote sensing monitoring method and the acoustic method are comparatively analyzed, so as to ensure the reliability of the experimental results (Li and Zhang, 2020; Wen et al., 2019; Xiao et al., 2019).

#### 3.1. Preparation for the Experiment

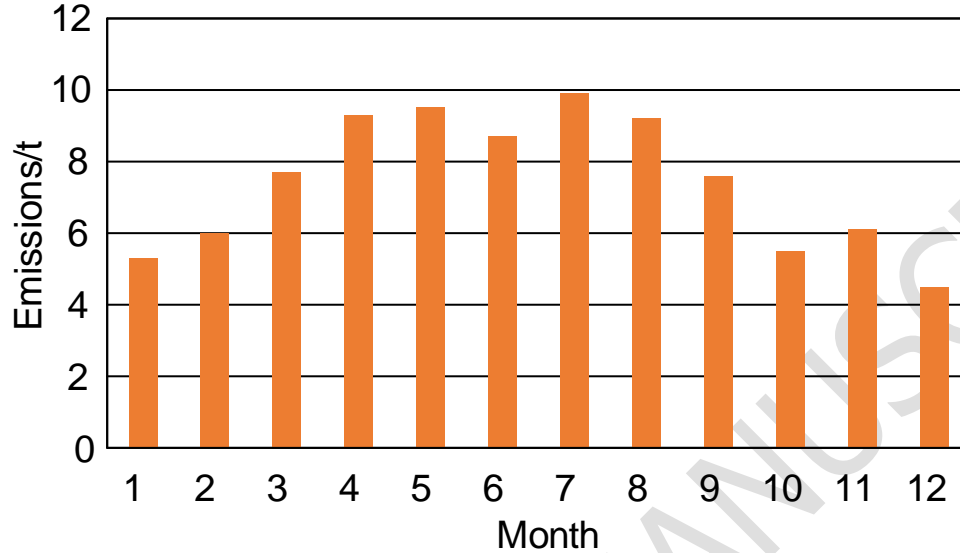
Before the experiment, we need to set the experimental environment. In 2008, Institute of Atmospheric Physics, Chinese Academy of Sciences completed and improved the atmospheric environment real-time monitoring network, which includes 17 ground stations and 6 sub stations on the tower. Eight stations in the monitoring network are selected to collect SF<sub>6</sub> emission samples. The specific location, surrounding conditions, observation time and effective sample number of each sampling point are shown in Table 3.

**Table 3.** Sampling points

Sampling point	Surrounding conditions	Sampling time	Number of valid samples
1	It is close to urban roads and residential areas	2019.5.26	102
2	Keep away from roads and residential areas	2019.6.10	109
3	It is close to the road and far from the residential area	2019.7.26	87

4	It is close to urban roads and residential areas	2019.8.01	135
5	It is far away from urban roads and residential areas	2019.9.13	149
6	Near site	2019.10.21	87
7	Close to school	2019.12.06	54

Taking the selected sampling points as the basic test environment, the historical data of SF<sub>6</sub> emission monitoring in the whole year of 2019 is obtained, as shown in Figure 5.



**Figure 5.** Historical data of SF<sub>6</sub> emission monitoring.

On the basis of the above experimental environment, MATLAB software is used to process the monitoring data. In order to ensure the accuracy of the later experimental results, it is necessary to maintain the consistency of the experimental conditions.

### 3.2. Analysis of Experimental Results

#### 3.2.1. Comparison of Monitoring Accuracy

In the above research, the near zero emission of SF<sub>6</sub> was monitored by nano sensor. In order to prove the effectiveness of the proposed method, different methods are tested by taking the monitoring accuracy as the experimental index, and the results are shown in Table 4.

**Table 4.** Comparison of monitoring accuracy of different methods

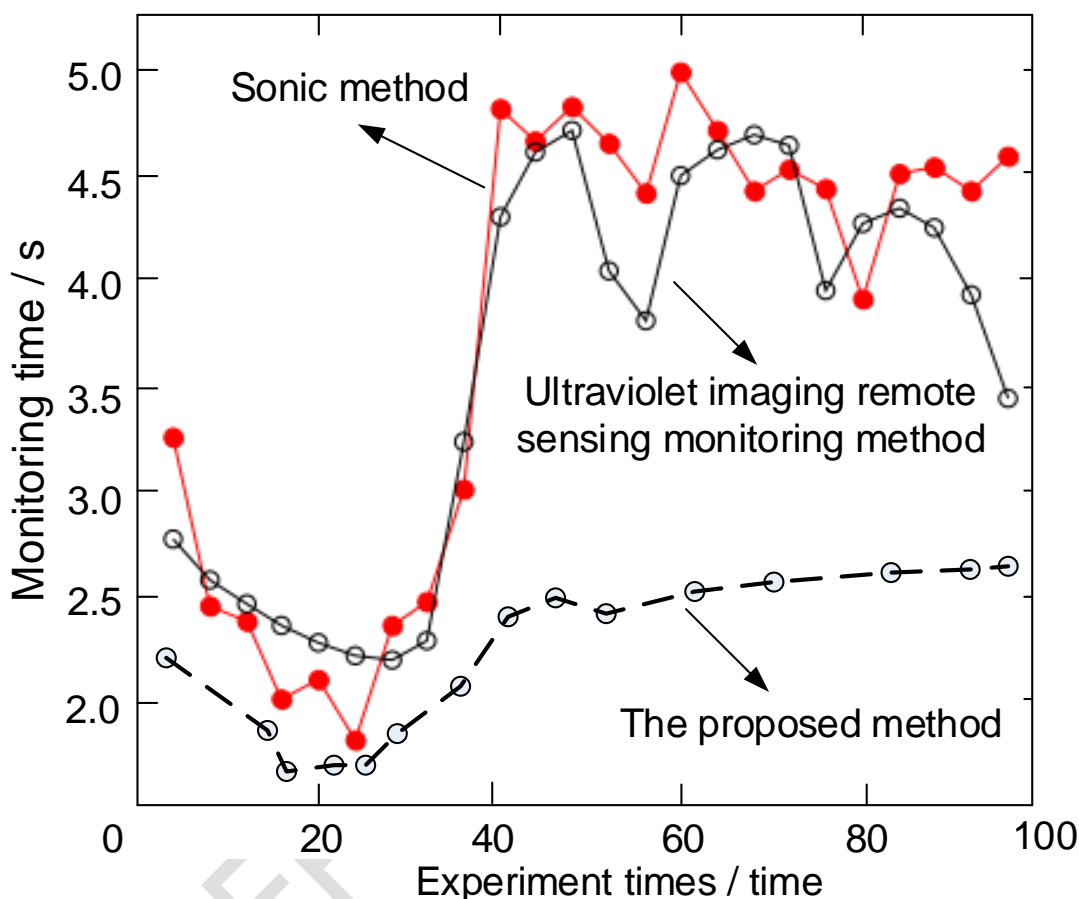
Experiment times/time	Monitoring accuracy/%		
	The proposed method	Ultraviolet imaging remote sensing monitoring method	Sonic method
10	81.56	76.15	73.28
20	88.21	77.93	73.56
30	90.43	78.40	74.21
40	91.12	78.59	74.59
50	91.17	79.85	75.02
60	92.25	80.16	75.67
70	91.36	80.26	76.04
80	92.03	81.45	76.29
90	92.94	81.59	77.06
100	92.99	82.37	78.93



According to the analysis of the data in Table 4, when the number of experiments is 50, the monitoring accuracy of the designed nano sensor method is 91.17%, 79.85% and 75.02%, respectively; When the number of experiments is 100, the monitoring accuracy of the proposed method, the ultraviolet imaging remote sensing method, and the acoustic method is 92.99%, 82.37% and 78.93%, respectively. The results show that the monitoring accuracy of the nano sensor method is significantly higher than that of the other two methods, indicating that the monitoring results of the nano sensor method are more reliable, which can provide reliable data basis for the study of gas emission and atmospheric environment monitoring.

### 3.2.2. Comparison of Monitoring Time

In order to prove the effectiveness of the proposed method, different methods are tested with the monitoring time as the experimental index, and the results are shown in Figure 6.



**Figure 6.** Comparison of monitoring time of different methods.

It can be seen from the analysis in Figure 6 that the monitoring time of the proposed nano sensor method is always lower than that of the ultraviolet imaging remote sensing method and the acoustic method. With the increase of the number of experiments, the monitoring time of the proposed method does not exceed 3.0 s, the maximum monitoring time of the ultraviolet imaging remote sensing method is more than 4.5 s, and the maximum monitoring time of the acoustic method is close to 5.0 s. The comparison shows that the proposed method has higher monitoring efficiency. This is due to that the proposed method uses nanosensor to monitor the near zero emission state of  $\text{SF}_6$ . The proposed method effectively overcomes the shortcomings of traditional chemiluminescence sensor which easily causes reagent consumption and shedding, thus reducing the influence of multiple factors on the monitoring process and improving the monitoring efficiency.

### 3.2.3. Monitoring Sensitivity

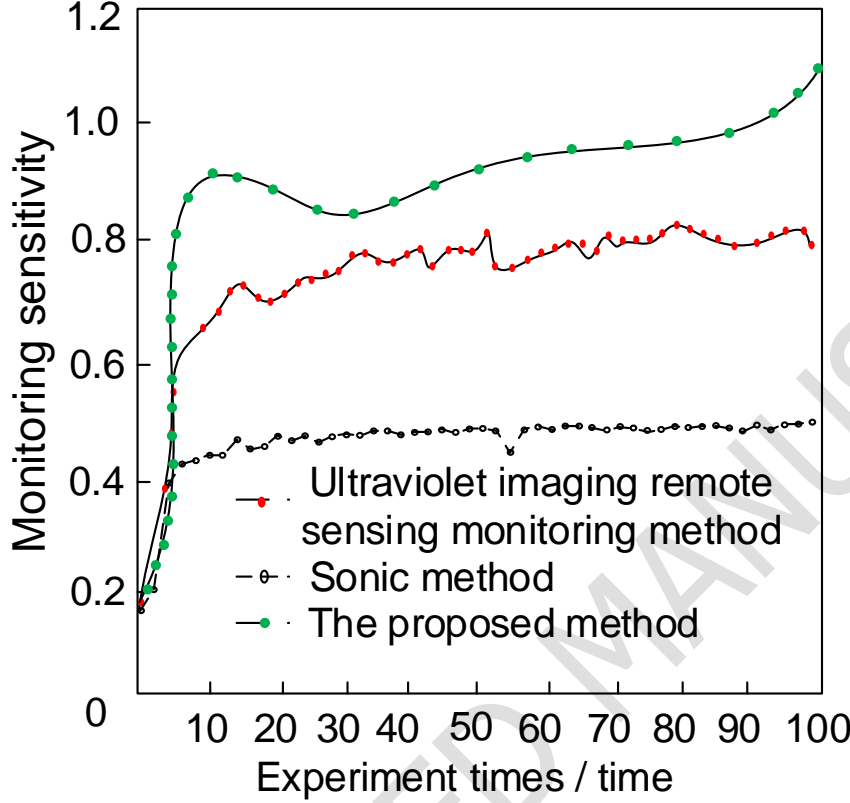
In order to further test the application performance of the nano sensor method, the performances of different methods in monitoring near zero emission of  $\text{SF}_6$  are comparatively analyzed by taking the monitoring sensitivity is used as the evaluation index.

The monitoring sensitivity is denoted by  $\delta_i$ , and the calculation formula is as follows:

$$\eta = \frac{S_\eta}{S_\varepsilon} \times t_i \quad (15)$$

Where  $S_\eta$  represents the reflected light from the monitoring sampling point;  $S_\varepsilon$  represents the distance between different monitoring sampling points;  $t_i$  represents the number of monitoring.

The comparison results of monitoring sensitivity of different methods are shown in Figure 7.



**Figure 7.** Comparison of monitoring sensitivity of different methods.

It can be seen from the analysis of Figure 7 that with the increase of the number of experiments, the monitoring time of different methods does not show a regular change trend, but on the whole, the monitoring sensitivity of the proposed method is significantly higher than that of the ultraviolet imaging remote sensing monitoring method and the acoustic method, indicating a better monitoring effect of proposed method.

In conclusion, the nano sensor method is superior to the traditional method in terms of monitoring time, monitoring sensitivity and monitoring accuracy, which fully verifies the practical application value of the nano sensor method.

#### 4. Conclusion

In recent years, studies have shown that the concentration of  $\text{SF}_6$  in the atmosphere is increasing rapidly at the rate of 7%~8%.  $\text{SF}_6$  in the atmosphere is mainly emitted by human activities, of which 80% comes from the insulators and high-voltage converters of electrical equipment, and the remaining 20% is mainly released from magnesium and aluminum industries (Okolie et al., 2019). The impact of  $\text{SF}_6$  on the atmospheric environment is mainly manifested by the greenhouse effect and the destruction of the ozone layer. At present, the issue of  $\text{SF}_6$  emission and control has received attention from all walks of life. Under the above background, this paper proposes Research on nano sensor for near zero emission monitoring of  $\text{SF}_6$ . The main research results are concluded as follows:

- In this work, we analyzed the characteristics of  $\text{SF}_6$  gas, and used the spectroscopic absorption method to conduct preliminary monitoring of  $\text{SF}_6$  gas emissions based on the analysis results.

- The lasy series Lasy-5 laser is used as the SF<sub>6</sub> gas monitoring hardware. The laser wavelength generated by the laser is just within the strongest absorption band of the SF<sub>6</sub> gas, which can meet the requirements of monitoring.
- The sensor array is designed according to the working principle of the nano sensor, and finally the monitoring of the near-zero emission of SF<sub>6</sub> is realized through the optimization of the nano sensor nodes.
- The experimental results show that the nano sensor method has significant advantages in monitoring accuracy, monitoring time and monitoring sensitivity, indicating that the method can be applied to gas emission monitoring, with better monitoring effect being achieved.

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