

Effect of flow and module configuration on SO₂ absorption by using membrane contactors

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Abstract

Sulfur dioxide (SO₂) emissions lead to negative environmental impacts and it is considered as an indicator for the larger group of gaseous sulfur oxides (SO_x) in the air. In this paper, the dimethylamine (DMA) solution was used as the absorbent in a α -Al₂O₃ hollow fiber membrane contactor that is operated under several conditions of gas velocity, liquid velocity, and 290 K operating temperature. The effects of gas and liquid phase properties and module configuration on SO₂ absorption efficiency in the hollow fiber membrane contactor were investigated. Simulation results showed that the changes of gas phase velocity, liquid phase velocity, and concentration have great influences on the absorption efficiency of SO₂. An increase of the gas flow rate decreases the SO₂ absorption efficiency, while an increase of the liquid flow rate has the opposite effect, increasing the efficiency. Because gas in the membrane module stays for a longer time, more absorption time promotes the gas and liquid reaction. However, the changes of the volume fraction of SO₂ in the mixed gas are not significant to SO₂ absorption. The simulation model could provide guidelines for selecting suitable fluid properties during the SO₂ absorption process in a hollow fiber membrane contactor.

Keywords: SO₂ Absorption; Hollow fiber membrane; Gas and liquid phases; Absorption efficiency; Numerical modelling

1. Introduction

Currently, fossil fuels (such as coal, oil, and natural gas) are the primary energy sources throughout the world. As a result, fuel combustion will continue to emit sulfur dioxide (SO₂) and nitrogen oxides (NO_x) at an astonishing annual rate. In addition, SO₂ emissions lead to acid rain, air pollution, urban smog, and harm to human health and ecosystems (Rahmani *et al.*, 2015; Bokotko *et al.*, 2005). Thus, it is very urgent to remove SO₂ from air. Currently, there are several common methods for SO₂ removal, i.e., wet scrubbing (Jin *et al.*, 2006; Andreasen *et al.*, 2007), dry scrubbing (Neather, 1996), and wet sulfuric acid process (Kikkawa *et al.*, 2002). But there are some shortcomings using these approaches, i.e., foaming, entrainment, flooding, and channeling issues, and a large required space (Mansourizadeh *et al.*, 2010). Membrane gas absorption (MGA) is an effective way for SO₂ removal which provides a large gas and liquid contact surface and a high packing density using a hollow fiber membrane contactor. In addition, the membrane only acts as a fixed interface while gases transport takes place across the membrane. Gas and

liquid can be operated separately using the contactor (Park *et al.*, 2007).

The MGA method was first employed in gas absorption in 1985 by Qi and Cussler (1985). The gas and liquid system was operated without flooding problems even at high gas flow rates. This was due to the indirect contact between gas and liquid. CO₂ capture using MGA method has been a popular topic and widely investigated (Zhang *et al.*, 2014, 2014a; Zhang, 2016). However, there were a few publications reported on the membrane absorption process of SO₂ (Park *et al.*, 2007; Luis *et al.*, 2010; Yu *et al.*, 2016).

Karoor and Sirkar, (1993) carried out SO₂ absorption experiments in pure water in a packed tower and a hollow fiber contactor. They found that efficient contacting was achieved in the case of a hollow fiber membrane contactor when compared to conventional reactors. In addition, the K_{La} value using MGA was around 10 times higher than that using conventional methods. Park *et al.* (Park *et al.*, 2008) performed a series of SO₂ absorption experiments in a polyvinylidene fluoride (PVDF) hollow fiber membrane. A variety of absorbents including NaOH, Na₂CO₃, Na₂SO₃, and NaHCO₃ solutions were compared regarding the SO₂ absorption performance. It was proved that the Na₂CO₃ solution showed the best performance for SO₂ absorption. Most previous studies have focused on experimental research and a few modeling works have been conducted (Luis *et al.*, 2010; Yu *et al.*, 2016; Fasihi *et al.*, 2012). Yu *et*

al. (2016) proposed a model for SO₂ absorption into water accompanied with reversible reaction in a hollow fiber membrane contactor and investigated the effects of inlet SO₂ concentration and temperature on the membrane performance. In our previous work (Zhang *et al.*, 2015), the effects of membrane and contactor geometry parameters on SO₂ absorption performance were studied theoretically. The proposed model could provide guidelines for selecting the optimum contactor parameters.

The purpose of this current work is to focus on the fluid dynamic properties and module configuration influences on SO₂ absorption efficiency in a hollow fiber membrane. The governing equations for material balances in three sections, i.e., the tube, membrane, and shell sides, were calculated and solved with the given boundary conditions. Three-dimensional concentration schematic is presented with different fluid dynamic parameters. The developed model could provide guidelines for selecting optimal fluids properties during SO₂ absorption process in a hollow fiber membrane contactor.

2. Hollow fiber membrane contactor

Figure 1 (a) shows a physical model of SO₂ absorption inside a hollow fiber membrane contactor. A mixed gas containing SO₂ and air entered into the module and reacted with the absorbent of dimethylamine (DMA). Figure 1 (b) describes the SO₂ transport process inside the hollow fiber membrane contactor.

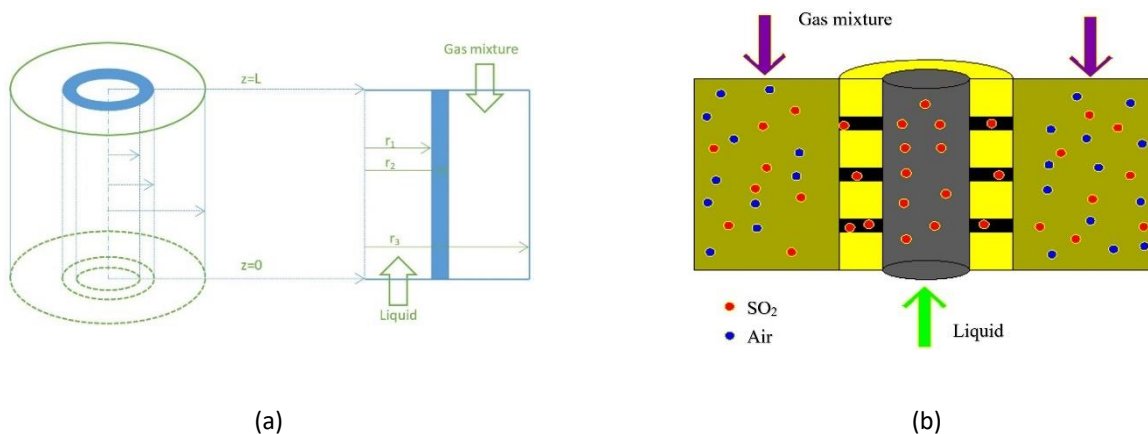


Figure 1. Hollow fiber membrane absorbing SO₂: (a) the internal structure and (b) gas and liquid flows

The mixed gas flowed out of the hollow fibers (shell side), and the absorbent flowed on the other side of the membrane contactor (tube side). Meanwhile, SO₂ was absorbed into the absorbent in the tube side to complete

the desulfurization after mixed gas entered into the membrane fibers. When gas and liquid were operated under the ideal conditions, the model could be simplified to the process of a hollow fiber absorbing SO₂. Mixed gas

with 5% SO₂ and air is considered under the conditions of 0.1 L min⁻¹ gas flow rate and 1 L min⁻¹ liquid flow rate.

3. Numerical Model

In this case, some assumptions are made to simplify the mass continuity equations for calculating the developed model:

1. The liquid phase in the tube is a steady flowing fluid under the isothermal condition, with stable physical properties, and the liquid velocity distribution in the tube presents a parabolic curve;
2. The effect of the axial diffusion and radial convective mass transfer is neglected;
3. The gas in the shell side is an ideal gas, and the fluid inside the tube is a Newtonian-type fluid;
4. Both the velocity distribution and the concentration distribution in the tube are axisymmetric;
5. The solute at the gas-liquid phase contact surface follows Henry's law.

3.1. The control equation of membrane

Since the membrane is hydrophobic, the SO₂ transport is considered in the non-wetted condition. Thus, the governing equation can be expressed as:

$$-D_{SO_2-M} \nabla \cdot (\nabla C_{SO_2-M}) = 0 \quad (1)$$

where C_{SO_2-M} is the SO₂ concentration, and D_{SO_2-M} is SO₂ diffusion coefficient in the membrane which can be written as:

$$D_{SO_2-M} = D_{SO_2-L} (\epsilon / \tau) \quad (2)$$

The axial velocity within the shell side can be expressed as (Zhang *et al.*, 2015):

$$V_{z-G} = 2V_{av-G} \left[1 - \left(\frac{r_2}{r_3} \right)^2 \right] \left[\frac{(r/r_3)^2 - (r_2/r_3)^2 + 2\ln(r_2/r)}{3 + (r_2/r_3)^4 - 4(r_2/r_3)^2 + 4\ln(r_2/r_3)} \right] \quad (8)$$

The boundary conditions inside the shell side are:

$$\text{at } r=r_2, \quad C_{SO_2-G} = C_{SO_2-M} \quad (9)$$

$$\text{at } r=r_e, \quad \partial C_{SO_2-G} / \partial r = 0 \quad (10)$$

(symmetric)

$$\text{at } z=L, \quad C_{SO_2-G} = C_0 \quad (11)$$

where C_0 is the initial concentration of SO₂ in the feed gas.

3.3. The control equation of tube side

The steady state continuity equation in the tube side can be represented as:

$$-D_{SO_2-L} \nabla \cdot (\nabla C_{SO_2-L}) + \nabla \cdot (C_{SO_2-L} V_{z-L}) = R_{SO_2} \quad (12)$$

where ϵ and τ represent the porosity and tortuosity of the used membrane material, respectively. The boundary conditions within the membrane domain are as follows:

$$\text{at } r = r_1, \quad C_{SO_2-M} = C_{SO_2-L} / m \quad (3)$$

$$\text{at } r = r_2, \quad C_{SO_2-M} = C_{SO_2-G} \quad (4)$$

$$\text{at } z = 0, L, \quad \partial C_{SO_2-M} / \partial z = 0 \quad (5)$$

where r_1 and r_2 are the inner and outer radii of fiber membrane, respectively. The third boundary condition means that both sides of the membrane section in the axial direction are impermeable.

3.2. The control equation of shell side

The steady state continuity equation of SO₂ flowing in the shell side can be expressed using Fick's law to estimate the diffusion flux, as follows:

$$-D_{SO_2-G} \nabla \cdot (\nabla C_{SO_2-G}) + \nabla \cdot (C_{SO_2-G} V_{z-G}) = 0 \quad (6)$$

where D_{SO_2-G} and C_{SO_2-G} denote the diffusion coefficient and the concentration of SO₂ in the gas phase, respectively. V_{z-G} represents the velocity of SO₂ inside the shell side in the z direction.

Assuming the principle of Happel free surface model, the radius of free surface can be expressed as (J. Viscous., 1959):

$$r_e = r_2 \sqrt{\frac{1}{\theta}} \quad (7)$$

where r_e is the radius of Happel free surface, and θ represents packed density of the membrane contactor.

where D_{SO_2-L} and C_{SO_2-L} represent the diffusion coefficient, and the concentration of SO₂ in liquid phase, respectively. In addition, V_{z-L} and R_{SO_2} denote the z -velocity of the inner tube and the gas-liquid reaction rate, respectively.

Assuming that the flow velocity inside the tube side is at a fully developed laminar flow state, the flow velocity distribution can be written as (Zhang *et al.*, 2015):

$$V_{z-L} = 2V_{av-L} \left[1 - \left(\frac{r}{r_1} \right)^2 \right] \quad (13)$$

where V_{av-L} is the average velocity in the z direction and r_1 is the inner radius of the hollow fiber membrane. The boundary conditions within the tube side can be expressed as:

$$\text{at } r = r_1, \quad C_{SO_2-L} = mC_{SO_2-M} \quad (14)$$

3.4. Reaction mechanisms

3.4.1 The reaction mechanism between SO₂ and water

The chemical reaction between SO₂ and water is (Roberts *et al.*, 1980):



where both k_E and k_E' are equilibrium constants. When the solution pH is lower than 4-5, the formation of SO_3^{2-} can be neglected. If the concentration of HSO_3^- is the same as H_3O^+ , the solution presents electrically neutral, and the expression of reaction rate can be written as:

$$-R_{SO_2} = k_1 C_{SO_2} - \frac{k_1}{k_E} (C_{HSO_3^-})^2 \quad (19)$$

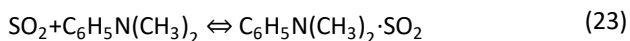
where the SO₂ ionization rate constant (k_1) is $3.17 \times 10^{-2} \text{ s}^{-1}$.

3.4.2 The reaction mechanism between SO₂ and DMA

In the chemical reaction between SO₂ and DMA, the following chemical reactions occur:



Besides, it is possible to produce extra chemical product during the chemical reaction between SO₂ and DMA. The chemical equation is (Basu and Dutta, 1987):



The reaction between the gas and liquid phases is not only an instantaneous reaction but also a reversible reaction at high DMA concentrations. And the pseudo-first-order reaction rate constant could be found in literature.

3.5. The model numerical solution method

$$\text{at } z = 0, \quad C_{SO_2-L} = 0, \quad C_{L-T} = C_{\text{initial}} \quad (15)$$

$$\text{at } r = 0, \quad \partial C_{SO_2-L} / \partial r = 0 \quad (\text{symmetric}) \quad (16)$$

where m is the dimensionless Henry coefficient between gas and liquid phases, C_{initial} is the initial concentration of the absorbent.

The parameters of the hollow fiber membrane contactor in this paper are presented in Table 1.

Table 1. Parameters of hollow fiber membrane contactor (Luis *et al.*, 2008).

Parameter	Symbol	Value
Fiber materials		$\alpha\text{-Al}_2\text{O}_3$
Canning material		316 stainless steel
Packing material		Epoxide resin
Fiber outside diameter (μm)	d_o	4000
Fiber inside diameter (μm)	d_i	3000
Fiber length (m)	L	0.44
Fiber number	n	280
Effective membrane contact area (m^2)	S	0.8
Fiber pore size (nm)	d_p	100

The finite element method using COMSOL Multiphysics software was applied in the numerical solution of the control equations in the developed model. The numerical solver UMFPACK is mainly used in meshing error control. It is a promote format of implicit time and is applied to solve the nonlinear, rigid and stiff boundary, which is also a good two-dimensional model numerical solver. The computer configuration of numerical simulation is a 64-bit operating system, with a 4.00GB memory space and Inter core AMD A8-4500M APU. Furthermore, Table 2 presents the physical and chemical properties of SO₂ as well as liquid absorbent, and reactive kinetic parameters between two phases. Figure 2 is the schematic diagram of triangular mesh

elements in the hollow fiber membrane contactor. The software generates a series of isotropic triangular grid with a triangle smallest unit and creates cells according to a certain proportion. There are 24156 grids in this figure.

Table 2. Diffusion coefficient and Henry's coefficient of SO₂ and DMA

Name	Parameter	Number	Reference
Henry's coefficient between SO ₂ and water	$m_{\text{SO}_2\text{-H}_2\text{O}}$	25.86	Hikita <i>et al.</i> , 1977
Diffusion coefficient between SO ₂ and water ($\text{m}^2 \text{s}^{-1}$)	$D_{\text{SO}_2\text{-H}_2\text{O}}$	2×10^{-9}	Dutta <i>et al.</i> , 1987
Henry's coefficient between SO ₂ and DMA solution	$m_{\text{SO}_2\text{-DMA}}$	0.00131	Koonaphapdeelert <i>et al.</i> , 2009
Diffusion coefficient between SO ₂ and DMA solution ($\text{m}^2 \text{s}^{-1}$)	$D_{\text{SO}_2\text{-DMA}}$	2.1×10^{-9}	Bird <i>et al.</i> , 2002
SO ₂ diffusion coefficient in the gas mixture ($\text{m}^2 \text{s}^{-1}$)	$D_{\text{SO}_2\text{-Gas}}$	1.26×10^{-5}	Luis <i>et al.</i> , 2010

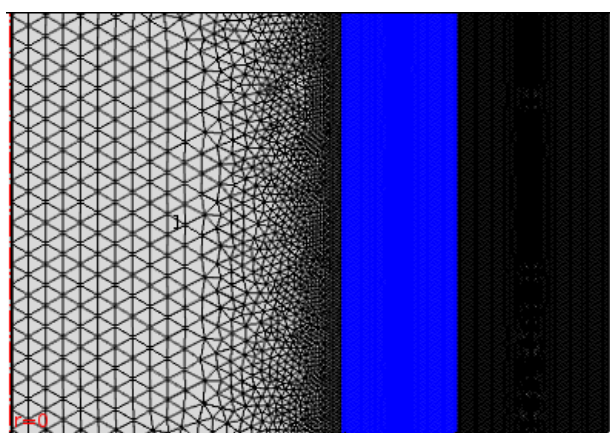


Figure 2. Schematic diagram of triangular mesh element in the membrane contactor

4.1 Concentration distributions

The visual description of the SO₂ concentration distribution inside the membrane contactor with three-dimensional concentration schematic is presented in Figures 3 (a-f). They showed the SO₂ three-dimensional concentration inside the membrane contactor when reacting with 2 mol L⁻¹ DMA solution at various gas velocities, respectively. As observed, the SO₂ concentration in the shell side of the membrane contactor gradually decreased from 2.0 to 1.06, 1.23, 1.35, 1.43, 1.48, and 1.53 mol L⁻¹. It was obvious that SO₂ in the mixed gas reacted continually with the DMA solutions, resulting in the continuous decrease in SO₂ concentration at the exit of the shell side. Figure 4 describes the concentration changes of SO₂ in the hollow fiber membrane. Its variation trend was similar to the

Meanwhile, the area with dense meshes means large changes in the fluid concentration. This is due to that the absorbent inside the tube side reacting with SO₂.

changes of SO₂ in shell side, decreasing from $z=L$ to $z=0$. According to Figure 5, the SO₂ concentration in the liquid phase increases from $z=0$ to $z=L$. This was due to the DMA solution absorbed SO₂ in the tube, and then the SO₂ concentration at the exit of tube reached to the highest value. Due to the concentration gradient of SO₂ between the tube and membrane sides, the SO₂ concentration gradually reduced from the interface between the tube and membrane sides to the central axis of the membrane contactor.

4.2 Effect of the gas flow velocity (model verification)

Figure 6 demonstrates the comparison between the simulation results of SO₂ removal efficiency and the experimental data reported in the literature (Luis *et al.*, 2010; Shirazian *et al.*, 2011) at different gas velocities.

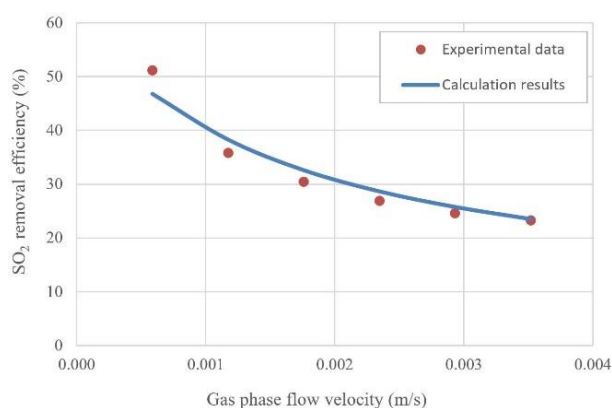


Fig. 6 Effect of the gas phase velocity on SO₂ absorption efficiency (mixed gas of 5% SO₂ and air, the liquid phase flow rate is 1 L min⁻¹, the operating temperature is 290K).

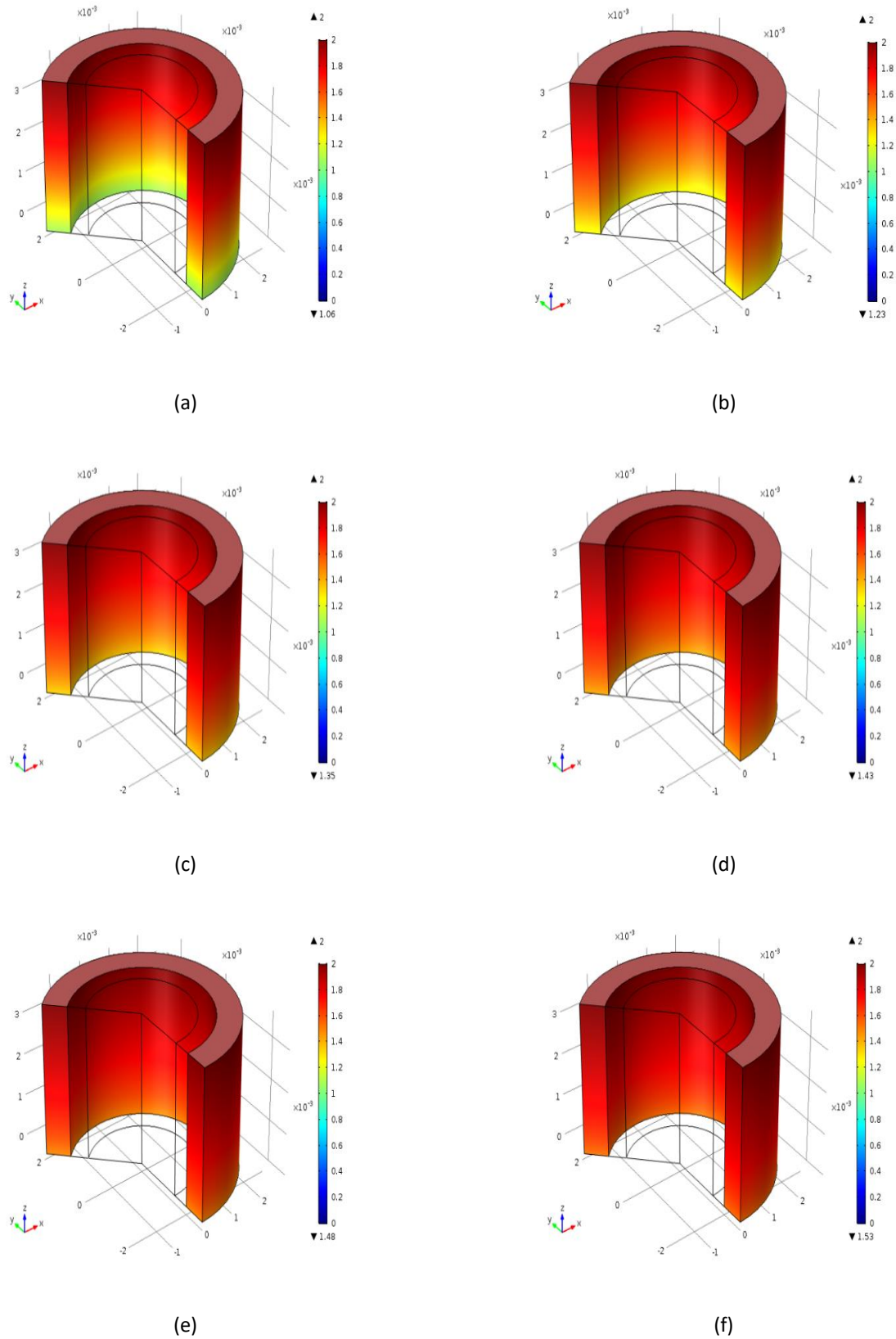


Figure 3. The three-dimensional concentration distribution of SO₂ reacting with DMA in the shell side (mixed gas of 5% SO₂ and air, the liquid phase flow rate is 1 L min⁻¹, the operating temperature is 290 K. V_g represents the gas phase flow velocity, a: $V_g=0.0006$ m s⁻¹; b: $V_g=0.0012$ m s⁻¹; c: $V_g=0.0018$ m s⁻¹; d: $V_g=0.0023$ m s⁻¹; e: $V_g=0.0029$ m s⁻¹; and f: $V_g=0.0035$ m s⁻¹)

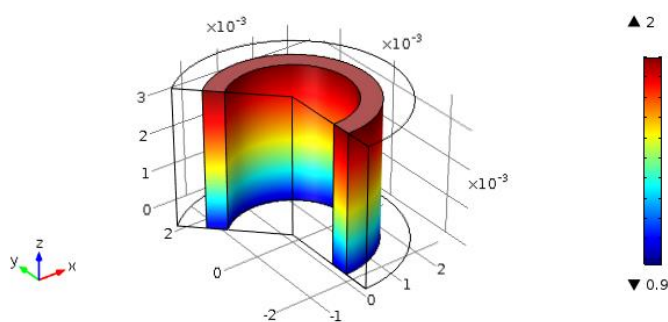


Figure 4. The SO₂ concentration distribution in the hollow fiber membrane contactor (mixed gas of 5% SO₂ and air, the liquid phase flow rate is 1 L min⁻¹, the gas phase flow rate is 0.1 L min⁻¹, the operating temperature is 290 K)

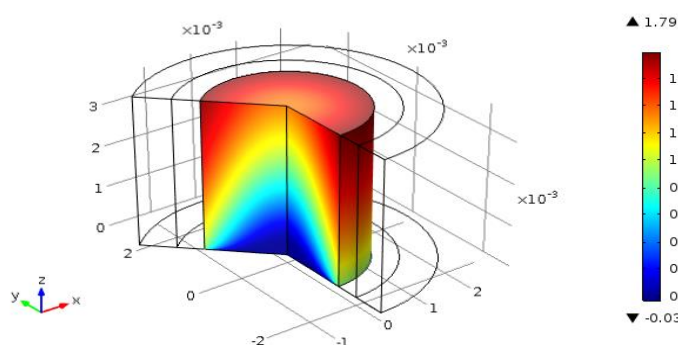


Figure 5. The three-dimensional concentration distribution diagram of the SO₂ concentration in tube side (mixed gas of 5% SO₂ and air, the gas phase flow rate is 0.1 L min⁻¹, the liquid phase flow rate is 1 L min⁻¹, the operating temperature is 290 K)

It can be seen from this figure that when the gas velocity increased from 0.0006 to 0.0035 m s⁻¹, SO₂ removal efficiency dramatically decreased from 46.82 to 23.5%. The reason was that when the velocity of gas phase increased, the gas and liquid reaction time reduced significantly. Although the SO₂ removal efficiency was high with a low gas velocity, the mass transfer effect of the whole process was relatively poor. The conclusion in literature (Eslami *et al.*, 2011; Faiz *et al.*, 2009) had a similar result trend. Figure 7 shows the influence of the gas phase velocity on SO₂ flux. As the gas velocity increased from 0.0006 to 0.0035 m s⁻¹, the absorbed flux of SO₂ decreased from 0.522 to 0.261 mol m⁻² h⁻¹. Thus, it was necessary to consider comprehensively the influence of the gas velocity on the removal efficiency and the mass transfer rate of SO₂ while selecting the optimal gas velocity conditions of the system.

4.3 Effect of the liquid phase velocity

The influence of the liquid phase velocity on SO₂ removal efficiency was examined from 0.0042 to 0.2528 m s⁻¹ using a 2 mol L⁻¹ DMA solution. As shown in Figure 8, the removal

efficiency increases constantly with increasing the liquid-phase flow velocity. This was because that with the increment in the liquid phase velocity, the disturbance of the liquid in the tube enhanced, and the thickness of boundary layer and the resistance for the liquid mass transfer decreased.

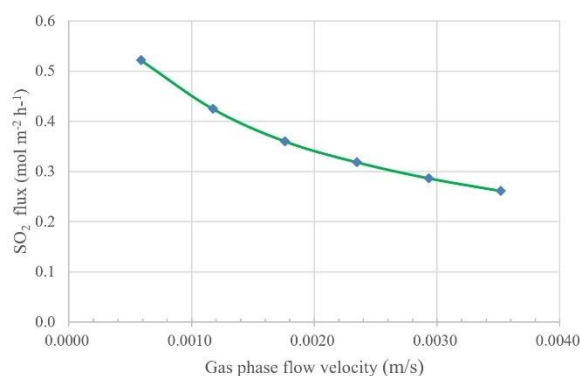


Fig. 7 Effect of the gas phase velocity on SO₂ flux (mixed gas of 5% SO₂ and air, the liquid phase flow rate is 1 L min⁻¹, the operating temperature is 290K).

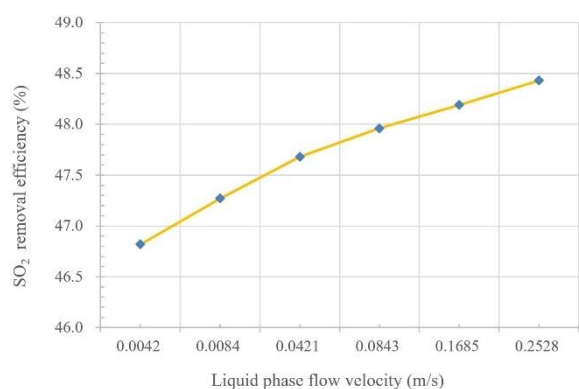


Fig. 8 Effect of the liquid phase velocity on SO₂ absorption efficiency (mixed gas of 5% SO₂ and air, the gas-phase flow rate is 0.1 L min⁻¹, the operating temperature is 290K).

Therefore, this was conducive to the uniform distribution of the liquid, and more fresh DMA solutions could react with SO₂ which finally improved the SO₂ removal efficiency. Although increasing the liquid phase velocity promoted the SO₂ absorption process, it was possible to increase the membrane wettability and the mass transfer resistance which deteriorated the absorption process. Thus, the liquid phase velocity should be controlled during the process of SO₂ absorption. This can not only avoid the wettability issue of the membrane to some extent, but also reduce the energy consumption in the process of SO₂ absorption.

4.4 Effect of SO₂ volume fraction

Table 3 demonstrates the influence of SO₂ volume fraction in the gas mixture on the removal efficiency. It was noted that the SO₂ removal efficiency remained around 46.82% while the SO₂ concentration increased from 0.15 to 4.8%. Therefore, in this case, the change in SO₂ volume fraction in mixed gas only had a slight effect on the SO₂ absorption efficiency within a certain range. Because under the given operating conditions of the experiment system, SO₂ content in the gas mixture was much less than air content

and there was no obvious effect on the whole removal process.

Table 3. The results of SO₂ absorption efficiency with different SO₂ volume fractions in the gas mixture (The gas phase velocity is 0.1 L min⁻¹, the liquid phase velocity is 1 L min⁻¹, the operating temperature is 290 K).

SO ₂ volume fraction (%)	SO ₂ absorption efficiency (%)
0.15	46.83
0.30	46.83
0.60	46.82
2.40	46.82
3.30	46.82
4.80	46.81

4.5 Effect of the number of the membrane contactors

In some cases, SO₂ absorption performance for a single membrane contactor was limited, increasing the number of the hollow fiber membrane contactor had a positive effect on SO₂ absorption. This was because considering the membrane contactors in series, the gas and liquid contact area increased and the gas and liquid reaction time in the contactor was longer (Zhang *et al.*, 2017, 2018). Thus, the SO₂ absorption efficiency improved.

Table 4 demonstrates the changes of SO₂ absorption efficiency in the cases of single and serial membrane contactors. The results revealed that the absorption efficiency using the membrane contactors in series was about 20% higher than that of for single one. However, in the actual production application, serial membrane contactors increased the investment and installation costs, and more space were needed for placing the membrane contactors. Furthermore, when selecting an optimal membrane contactor, the influences of the absorption efficiency and the lowest cost should be comprehensively considered.

Table 4. Comparisons of SO₂ absorption efficiency with various numbers of the membrane contactor (mixed gas of 5% SO₂ and air, the liquid phase flow rate is 1 L min⁻¹, the operating temperature is 290 K).

Gas velocity (m s ⁻¹)	SO ₂ removal efficiency for a single membrane contactor (%)	SO ₂ removal efficiency for the serial membrane contactors (%)
0.0006	46.82	63.15
0.0012	38.30	61.95
0.0018	32.60	54.50

4. Conclusions

Regarding the atmospheric pollution caused by SO₂, this paper uses a promising method of membrane absorption. The effect of the gas and liquid flows properties and the module configuration on SO₂ absorption was investigated numerically.

In this study, a three-dimensional distribution of SO₂ concentration in the hollow fiber membrane contactor was observed visually by applying a CFD model. The distribution of SO₂ concentration was shown intuitively with changing the gas and liquid phase parameters. Then, the model validation was carried out between the experimental data and the simulation results at different gas flow velocities. It showed that the developed model was feasible and reliable. The simulation results indicated that as increasing the gas phase velocity or SO₂ volume fraction in the gas mixture, the SO₂ absorption efficiency presented a descending tendency; as increasing the liquid phase velocity, SO₂ removal efficiency showed an upward tendency; as considering the membrane contactors in series, the SO₂ removal efficiency increased apparently. Finally, this model could efficiently predict the influence of the gas and liquid parameters and the module configuration on SO₂ absorption, which could optimize the system data and provide guidelines for the operation of the actual application in the future.

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Nomenclature

D	diffusion coefficient (m ² s ⁻¹)
V	velocity (m s ⁻¹)
C	concentration (mol m ⁻³)
k	reaction rate constant (m ³ mol ⁻¹ s ⁻¹)
m	solubility
p	membrane pore
r	radial distance (μm)

R overall reaction rate (mol m⁻³ s⁻¹)

T temperature (K)

ε membrane porosity

τ tortuosity factor

Subscripts

av average

G gas phase

L liquid phase

M membrane

T tube

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